

## AM 0219: Nonlinear Dynamical Systems

Differentiation of the solution to an initial-value problem with respect to initial time

**Exercise 19:** Consider a continuously differentiable vector field  $f : X \times \mathbb{R} \rightarrow X = \mathbb{R}^n$ . Let  $x(t, t_0)$  denote the solution at time  $t$  of the associated initial-value problem

$$\dot{x}(t) = f(x(t), t), \quad x(t_0) = x_0.$$

Prove: For any fixed  $\tau$  such that  $x(\tau + t_0, t_0)$  exists, there exists a neighborhood  $U$  of  $t_0$  such that the map

$$(t_0 - \varepsilon, t_0 + \varepsilon) \rightarrow X, \quad s \mapsto x(\tau + s, s),$$

is differentiable with respect to  $s$ , for  $s \in U$ . Which differential equation is solved by  $v(t) := D_{t_0}x(t + t_0, t_0)$  ?

**Solution A:** [Direct approach]

$$\begin{aligned} x(t) &= x(t, t_0) = x_0 + \int_{t_0}^t f(x(\varsigma), \varsigma) \, d\varsigma \\ &= x_0 + \int_{t_0}^t f(x(\varsigma), \varsigma) \, d\varsigma = F(x(\cdot), t_0)(t) \end{aligned}$$

$F$  is differentiable w.r.t.  $x(\cdot)$  and  $t_0$ . Banach's Fixed-Point Theorem implies

$$w = D_{t_0}x(\cdot, t_0) = D_{t_0}x = \left( \text{Id} - \partial_{x(\cdot)}F \Big|_{(x, t_0)} \right)^{-1} \partial_{t_0}F \Big|_{(x, t_0)},$$

and therefore

$$w = \partial_{x(\cdot)}F \Big|_{(x, t_0)} w + \partial_{t_0}F \Big|_{(x, t_0)}.$$

Thus

$$w(t) = \int_{t_0}^t \partial_x f(x(\varsigma), \varsigma) w(\varsigma) \, d\varsigma - f(x(t_0), t_0)$$

and

$$\begin{aligned} v(t) &= D_{t_0}x(t + t_0, t_0) = w(t + t_0) + f(x(t + t_0), t + t_0) \\ &= \int_{t_0}^{t+t_0} \partial_x f(x(\varsigma), \varsigma) \left( v(\varsigma - t_0) - f(x(\varsigma), \varsigma) \right) \, d\varsigma - f(x(t_0), t_0) + f(x(t + t_0), t + t_0) \\ &= \int_{t_0}^{t+t_0} \partial_x f(x(\varsigma), \varsigma) v(\varsigma - t_0) \, d\varsigma - \int_{t_0}^{t+t_0} \left( D_\varsigma f(x(\varsigma), \varsigma) - \partial_t f(x(\varsigma), \varsigma) \right) \, d\varsigma \\ &\quad - f(x(t_0), t_0) + f(x(t + t_0), t + t_0) \\ &= \int_0^t \partial_x f(x(\varsigma + t_0), \varsigma + t_0) v(\varsigma) \, d\varsigma + \int_0^t \partial_t f(x(\varsigma + t_0), \varsigma + t_0) \, d\varsigma \end{aligned}$$

and finally

$$\begin{aligned} \dot{v}(t) &= \partial_x f(x(t + t_0, t_0), t + t_0) \cdot v(t) + \partial_t f(x(t + t_0, t_0), t + t_0), \\ v(0) &= 0. \end{aligned}$$

**Solution B:** [Differentiation w.r.t. initial condition]

$$x(t) = x_0 + \int_{t_0}^t f(x(\varsigma), \varsigma) \, d\varsigma.$$

A change of the initial time corresponds to a change of the initial value in direction of the vector field. That can be seen by inverting the flow direction:

$$x(t_0) = x(t) + \int_t^{t_0} f(x(\varsigma), \varsigma) \, d\varsigma,$$

hence

$$w = D_{t_0}x(\cdot, t_0, x_0) = -D_{x_0}x(\cdot, t_0, x_0) \cdot f(x_0, t_0)$$

solves the variational equation

$$\dot{w}(t) = \partial_x f(x(t), t) \cdot w(t), \quad w(t_0) = -f(x_0, t_0).$$

As before

$$v(t) = D_{t_0}x(t + t_0, t_0) = w(t + t_0) + f(x(t + t_0), t + t_0).$$

Therefore

$$\begin{aligned} \dot{v}(t - t_0) &= \partial_x f(x(t), t) \cdot w(t) + \partial_x f(x(t), t) \cdot \dot{x}(t) + \partial_t f(x(t), t) \\ &= \partial_x f(x(t), t) \cdot (v(t - t_0) - f(x(t), t)) + \partial_x f(x(t), t) \cdot f(x(t), t) + \partial_t f(x(t), t) \end{aligned}$$

and finally

$$\begin{aligned} \dot{v}(t) &= \partial_x f(x(t + t_0, t_0), t + t_0) \cdot v(t) + \partial_t f(x(t + t_0, t_0), t + t_0), \\ v(0) &= 0. \end{aligned}$$

**Solution C:** [Differentiation w.r.t. parameter]

$$\begin{aligned} \tilde{x}(t) &= x(t + t_0, t_0) = x_0 + \int_0^t f(x(\varsigma + t_0, t_0), \varsigma + t_0) \, d\varsigma \\ &= x_0 + \int_0^t f(\tilde{x}(\varsigma), \varsigma + t_0) \, d\varsigma = F(\tilde{x}(\cdot), t_0)(t) \end{aligned}$$

$F$  is differentiable w.r.t.  $\tilde{x}(\cdot)$  and  $t_0$ . Banach's Fixed-Point Theorem implies

$$v = D_{t_0}x(\cdot + t_0, t_0) = D_{t_0}\tilde{x} = \left( \text{Id} - \partial_{\tilde{x}(\cdot)}F|_{(\tilde{x}, t_0)} \right)^{-1} \partial_{t_0}F|_{(\tilde{x}, t_0)},$$

and therefore

$$v = \partial_{\tilde{x}(\cdot)}F|_{(\tilde{x}, t_0)} v + \partial_{t_0}F|_{(\tilde{x}, t_0)}.$$

Thus

$$v(t) = \int_0^t \partial_x f(\tilde{x}(\varsigma), \varsigma + t_0) v(\varsigma) \, d\varsigma + \int_0^t \partial_t f(\tilde{x}(\varsigma), \varsigma + t_0) \, d\varsigma$$

and finally

$$\begin{aligned} \dot{v}(t) &= \partial_x f(x(t + t_0, t_0), t + t_0) \cdot v(t) + \partial_t f(x(t + t_0, t_0), t + t_0), \\ v(0) &= 0. \end{aligned}$$

**Solution D:** [Differentiation w.r.t. vector field]

$$v = D_{t_0}x(\cdot + t_0, t_0) = D_f x(\cdot, f)g \quad \text{with} \quad g = \partial_t f.$$

Again

$$x(t) = x(t, f) = x_0 + \int_{t_0}^{t+t_0} f(x(\varsigma, t_0), \varsigma) d\varsigma = F(x(\cdot), f)(t)$$

$F$  is differentiable w.r.t.  $x(\cdot)$  and  $f$ . Banach's Fixed-Point Theorem implies

$$v = D_f x(\cdot)g = \left( \text{Id} - \partial_{x(\cdot)} F \Big|_{(x, f)} \right)^{-1} \partial_f F \Big|_{(x, f)} g,$$

and therefore

$$v = \partial_{x(\cdot)} F \Big|_{(x, t_0)} v + \partial_f F \Big|_{(x, t_0)} g.$$

Thus

$$v(t) = \int_{t_0}^{t+t_0} \partial_x f(x(\varsigma), \varsigma) v(\varsigma - t_0) d\varsigma + \int_{t_0}^{t+t_0} g(x(\varsigma), \varsigma) d\varsigma$$

and finally (using  $g = \partial_t f$ )

$$\begin{aligned} \dot{v}(t) &= \partial_x f(x(t + t_0, t_0), t + t_0) \cdot v(t) + \partial_t f(x(t + t_0, t_0), t + t_0), \\ v(0) &= 0. \end{aligned}$$