

Exercises

AM 0219: Nonlinear Dynamical Systems

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due date: Mon, Sep 20, 2004

Exercise 1: Consider a flow $\varphi(t, x) = \varphi_t(x)$ on the real axis, $x \in \mathbb{R}$.

- (i) Prove or disprove: every periodic orbit is an equilibrium, i.e.

$$\forall x_0 \in \mathbb{R} \quad \left(\exists p > 0 : \varphi(p, x_0) = x_0 \implies \forall t \in \mathbb{R} : \varphi(t, x_0) = x_0 \right)$$

- (ii) What are possible α -limits and ω -limits of an orbit of φ ? (Consider bounded and unbounded orbits.)

Exercise 2: Consider a flow φ on \mathbb{R}^n , $n \geq 2$. The orbit $\varphi_t(x_0)$ of x_0 is assumed to have arbitrarily small periods, i.e.

$$\forall \varepsilon > 0 \quad \exists 0 < p < \varepsilon : \varphi_p(x_0) = x_0.$$

Prove: x_0 is an equilibrium.

Exercise 3: Let φ be a flow on $X = \mathbb{R}^n$. Sets of the form

$$\gamma(x_0) = \{ (t, \varphi(t, x_0)) : t \in \mathbb{R} \} \subset \mathbb{R} \times X$$

are called solution curves. Define the time shift S_ϑ on the extended phase space $\mathbb{R} \times X$ by

$$S_\vartheta : \mathbb{R} \times X \rightarrow \mathbb{R} \times X, \quad (t, x) \mapsto (t + \vartheta, x).$$

- (i) Prove: the shift S_ϑ maps solution curves onto solution curves, for any fixed ϑ .
- (ii) Which solution curves remain fixed under *a particular* S_ϑ ? Which solution curves remain fixed under *all* S_ϑ ?

Exercise 4: The flow $\varphi : \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$ of the mathematical pendulum corresponds to the vector field

$$\begin{pmatrix} \dot{x} \\ \dot{v} \end{pmatrix} = \begin{pmatrix} v \\ -\sin x \end{pmatrix}.$$

Prove: the flow φ is *equivariant* under translations by 2π , i.e.

$$\varphi \left(t, \begin{pmatrix} x \\ v \end{pmatrix} + \begin{pmatrix} 2\pi \\ 0 \end{pmatrix} \right) = \varphi \left(t, \begin{pmatrix} x \\ v \end{pmatrix} \right) + \begin{pmatrix} 2\pi \\ 0 \end{pmatrix}, \quad \text{for all } t, x, v.$$

Hint: You may use the uniqueness of the solution of the initial-value problem without proof.