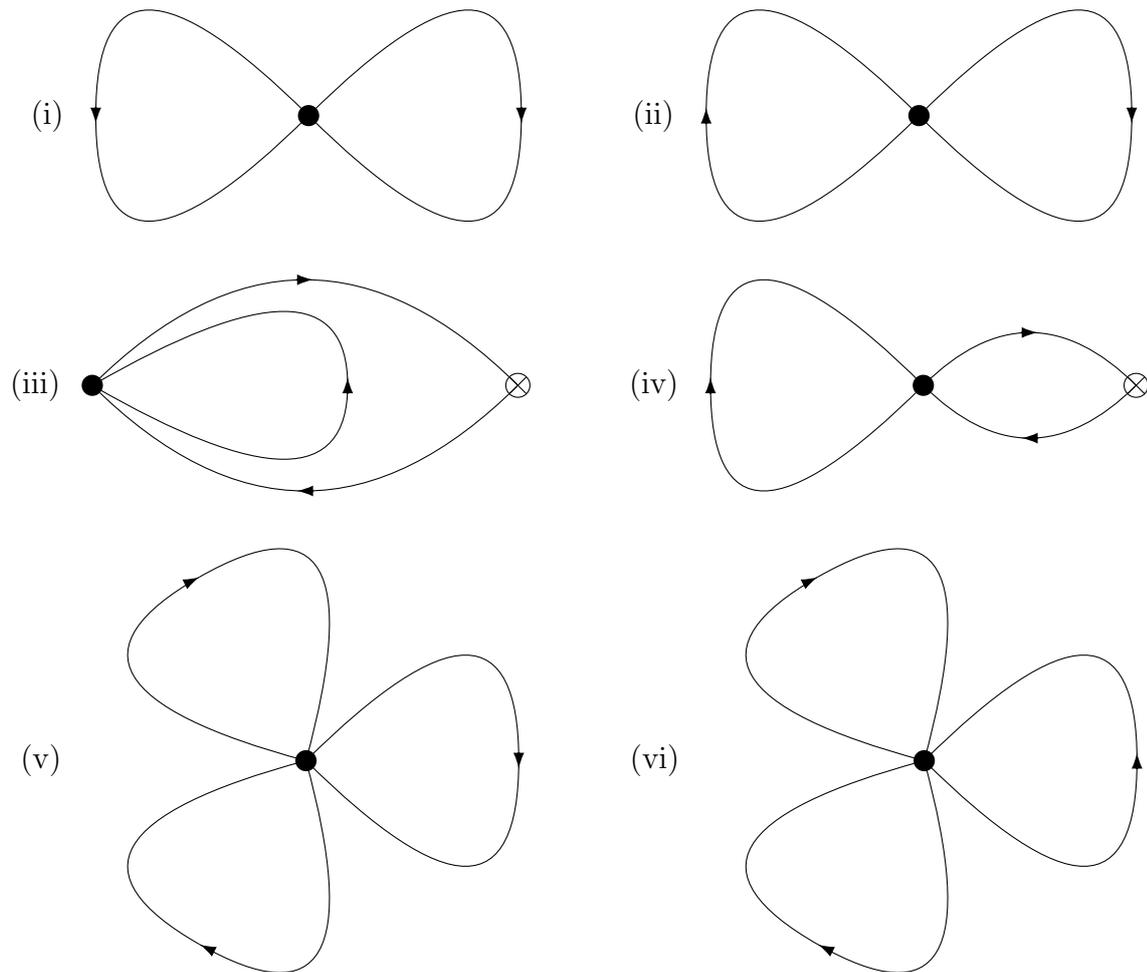


Homework assignment
Dynamical Systems
 Bernold Fiedler, Stefan Liebscher
<http://dynamics.mi.fu-berlin.de/lectures/>
due date: Friday, July 2, 2010

Problem 41: Which of the following sets are possible ω -limits of a (single) trajectory of some planar flow? Which of the sets cannot occur as ω -limits (of a single trajectory)? Justify your claims, without providing explicit vector fields.



Discs \bullet denote equilibria (of any type) and crossed out circles \otimes denote hyperbolic saddles.

Problem 42: Let $A \subseteq B \subseteq X = \mathbb{R}^N$ be sets and φ_t a flow on X . The set A is called *chain-recurrent* with respect to B if for every $y_0 \in A$ and every $\varepsilon > 0$, $T > 0$ there exists a positive number $n \in \mathbb{N}$, a sequence of times $t_0, \dots, t_{n-1} \geq T$, and points $y_1, \dots, y_{n-1} \in B$ such that

$$\text{dist}(\varphi_{t_i}(y_i), y_{i+1}) < \varepsilon, \quad i = 0, \dots, n-1 \pmod{n}, \text{ i.e. } y_n := y_0.$$

The set A is called *recurrent*, if we can choose chains of length $n = 1$ for all points, i.e. if $y_0 \in \omega(y_0)$ for all $y_0 \in A$.

Prove: For any $x_0 \in X$, the ω -limit $\omega(x_0)$ is chain-recurrent with respect to X , but it is not necessarily recurrent.

Extra credit: Let the trajectory $\varphi_t(x_0)$ be bounded. Prove or disprove: The ω -limit $\omega(x_0)$ is chain-recurrent with respect to *itself*.

Problem 43: Choose at least one variant:

- (A) In a bounded planar classroom, a student with a difficult question chases a professor. Both run at constant velocity 1 in arbitrary (and variable) direction. Can the student reach the professor?
- (B) The athletic professor runs along a circle in \mathbb{R}^2 , with constant velocity 1. The student starts at the center and keeps running towards the current position of the professor, at constant velocity $p < 1$. What is the student's ω -limit set? Is the ω -limit set stable? What happens for $p = 1$, $p > 1$?

Hint (B): Useful coordinates are the angle between origin and student, as seen from the professor, and the distance between student and professor.

Extra "credit": Chase the student.

Problem 44: Consider again the Feinberg result on reversible chemical networks of deficiency zero as discussed in class:

$$\dot{x} = \sum_{y \rightarrow y'} k_{y \rightarrow y'} x^y (y' - y),$$

with concentrations $x \in \mathbb{R}_+^n$, stoichiometric coefficients $y \in \mathbb{N}_0^n$, and reaction rates $k_{y \rightarrow y'}$. Given an initial value $x(0) \in \mathbb{R}_+^n$ with positive components, the stoichiometric subspace $(S + x(0)) \cap \mathbb{R}_+^n$,

$$S = \text{span} \{ y' - y \mid k_{y \rightarrow y'} > 0 \},$$

is invariant and contains a unique equilibrium x^* . Furthermore, there exists a strict Lyapunov function

$$V(x) = \sum_{i=1}^n x_i (\log x_i - \log x_i^* - 1)$$

on $(S + x(0)) \cap \mathbb{R}_+^n$.

Prove that these claims imply that the equilibrium x^* is (locally) asymptotically stable in $S + x(0)$.