Basic Questions of Dynamical Systems II

- 1. What is a Poincaré section to a periodic orbit of a flow?
- 2. What is a Poincaré map to a periodic orbit of a flow?
- 3. Formulate the Floquet theorem for a non-autonomous, time periodic, linear differential equation.
- 4. Formulate the Floquet theorem for an autonomous vector field, linearized at a periodic orbit.
- 5. What are Floquet multipliers and Floquet exponents of a periodic orbits of an autonomous vector field?
- 6. Why do periodic orbits of an autonomous vector field possess a trivial Floquet multiplier 1?
- 7. How is the rotation number of an (orientation preserving) homeomorphism $f: S^1 \to S^1$ defined?
- 8. How are existence and periods of periodic points related to the rotation number of a homeomorphism $f: S^1 \to S^1$?
- 9. Formulate the theorem of Denjoy for C^2 -diffeomorphisms $f: S^1 \to S^1$.
- 10. How are local/global stable and unstable manifolds on a hyperbolic equilibrium of a vector field defined?
- 11. Formulate the theorem on the existence of local stable and unstable manifolds to a hyperbolic equilibrium of a vector field.
- 12. Formulate the theorem on the existence of local stable and unstable manifolds to a hyperbolic fixed point of a diffeomorphism.
- 13. Are stable and unstable manifolds to a hyperbolic equilibrium unique? What are the tangent spaces to stable and unstable manifolds at the equilibrium?
- 14. What is the (Bernoulli) shift on N symbols? Define the shift space, its topology, and the shift map.

- 15. How can we construct
 - (a) periodic orbits of every period
 - (b) a dense set of periodic orbits
 - (c) a dense orbit
 - for the shift on 2 symbols?
- 16. How does the shift on 2 symbols illustrate recurrence as well as sensitive dependence on initial conditions?
- 17. What is the Smale horseshoe?
- 18. Formulate the theorem on the embedding of the shift into a C^0 horseshoe.
- 19. Formulate the theorem on the embedding of the shift into a C^1 horseshoe.
- 20. Sketch a horseshoe construction for the bouncing-ball map

$$\Phi_{k+1} = \Phi_k + v_k, v_{k+1} = v_k - \gamma \cos(\Phi_k + v_k),$$

under a suitable assumption on γ .

- 21. How is a hyperbolic structure defined?
- 22. What is a transverse homoclinic point of a diffeomorphism?
- 23. Formulate the λ -lemma.
- 24. How does a transverse homoclinic point give rise to shift dynamics? Sketch the relevant picture.
- 25. What is the Plykin attractor?
- 26. How is C^1 structural stability of a diffeomorphism defined?
- 27. Give at least two examples of structurally stable diffeomorphisms of the 2-torus.
- 28. Sketch the geodesic flow on the Lobachevsky plane. What are the horocycles? What is their dynamic significance?
- 29. What is a strange attractor? Sketch an example and list relevant properties.

- 30. Formulate Brouwer's fixed-point theorem.
- 31. How is the local center manifold to a non-hyperbolic equilibrium of a vector field defined?
- 32. Formulate the theorem on the existence of a local center manifold to a non-hyperbolic equilibrium of a vector field.
- 33. Formulate the theorem on the existence of a local center manifold to a non-hyperbolic fixed point of a diffeomorphism.
- 34. Under which assumptions on the vector field does a global center manifold to a non-hyperbolic equilibrium exist? Is the global center manifold unique?
- 35. Is the local center manifold to a non-hyperbolic equilibrium unique? What is the tangent space to a C^1 center manifold at the equilibrium?
- 36. How are the local center-stable and center-unstable manifolds to a non-hyperbolic equilibrium of a vector field defined? When do they exist?
- 37. Let A be the linearization of a C^1 vector field on \mathbb{R}^n at the equilibrium x = 0. Suppose the only purely imaginary eigenvalue of A is a simple eigenvalue zero. Can the vector field possess periodic orbits arbitrarily near x = 0?
- 38. Let A be the linearization of a C^1 vector field on \mathbb{R}^n at the equilibrium x = 0. Suppose the only purely imaginary eigenvalues of A are $\pm i$, both simple. Can the vector field possess periodic orbits arbitrarily near x = 0?
- 39. How can the (global) center manifold be written as a fixed point of a contraction map on a suitable function space? Define the space and the contraction map.