

### 3. Exercise for Differential Equations I (SS 2016 V th)

Please finish until: Friday, May 13, 2016

**Exercise 11.** Calculate the general solution of the following differential equations:

- a)  $tx' = x(\ln x - \ln t)$ . (2 points)  
b)  $2t^2x' = t^2 + x^2$ . (2 points)  
c)  $tx' = x + \sqrt{t^2 - x^2}$ . (2 points)

**Exercise 12.** Show that the task to calculate the solution of the scalar equation

$$x' = f\left(\frac{at + bx + \gamma}{ct + dx + \delta}\right)$$

can always be reduced to calculate the solution of an equation with separated variables. More precisely, proceed as follows:

- a) If  $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} \neq 0$ , use the substitution

$$y(t) = \frac{x(t - t_0) + x_0}{t},$$

(here,  $x(t - t_0)$  means  $x$  evaluated at  $t - t_0$ , not a product), where  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} t_0 \\ x_0 \end{pmatrix} = \begin{pmatrix} \gamma \\ \delta \end{pmatrix}$ , and differentiate  $ty(t)$  to obtain eventually a differential equation for  $y$ . (4 points)

*Remark.* Alternatively, you can also use the substitution  $z(t) = x(t - t_0) + x_0$  to reduce the problem to a 0-homogeneous equation for  $z$ . However, as you have seen in the lecture, you will have to use a further substitution to obtain an equation with separated variables. Both approaches are actually just a different notation for the same thing, because  $y(t) = z(t)/t$  corresponds exactly to the substitution from the lecture.

- b) If  $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = 0$  use after some case distinction a rather obvious substitution in each case. (3 points)

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**Exercise 13.** Let  $M \subseteq \mathbb{R}^N$ , and let  $f: M \rightarrow \mathbb{R}^N$  and  $\mu: M \rightarrow \mathbb{R} \setminus \{0\}$  be continuous. The aim of this exercise is to show that the autonomous system

$$\dot{x} = f(x) \quad (*)$$

and the “scaled by the scalar factor  $\mu \neq 0$ ” system

$$\dot{y} = \mu(y)f(y) \quad (**)$$

have the same trajectories: The solutions differ only up to a rescaling of time (in case  $\mu(y(t)) > 0$  for all  $t$ ) or rescaling and inversion of time (in case  $\mu(y(t)) < 0$ ), respectively.

More precisely, show the following assertions:

- a) If  $x$  is a solution of (\*) in an interval  $(a, b) \ni s_0$  and  $\varphi$  is a solution of the autonomous 1-dimensional initial value problem

$$\varphi'(s) = \mu(x(\varphi(s))), \quad \varphi(t_0) = s_0, \quad (***)$$

then  $\varphi: (a, b) \rightarrow (\alpha, \beta) \ni t_0$  is a diffeomorphism for appropriate numbers  $\alpha < \beta$ , and the time-reparametrization  $y := x \circ \varphi$ , that is  $y(t) := x(\varphi(t))$ , is a solution of (\*\*). (2 + 2 points)

- b) Conversely, if  $y$  is a solution of (\*\*) in an interval  $(\alpha, \beta) \ni t_0$  and

$$\psi(t) := s_0 + \int_{t_0}^t \mu(y(\tau)) d\tau,$$

then  $\psi: (\alpha, \beta) \rightarrow (a, b) \ni s_0$  is a diffeomorphism with appropriate numbers  $a < b$ , and with  $\varphi := \psi^{-1}$  the time reparametrization  $x = y \circ \varphi$  is a solution of (\*). (2 points + 3 extra points)

Obviously, the solution  $x$  on  $(a, b)$  produces the same trajectory as the solution  $y$  on  $(\alpha, \beta)$ , and the solutions pass through the trajectory in the same (or opposite) direction if and only if  $\varphi', \psi' > 0$  (or  $< 0$ , respectively). The latter holds if and only if  $\mu \circ y > 0$  (or  $< 0$ ) on  $(\alpha, \beta)$ , respectively.

**Exercise 14.** Note that Exercise 13 implies in particular that the idea of Euler multipliers can also be used for Hamiltonian systems: The systems

$$\begin{aligned} \dot{x} &= G(x, y) \\ \dot{y} &= -F(x, y) \end{aligned}$$

and

$$\begin{aligned} \dot{x} &= \mu(x, y)G(x, y) \\ \dot{y} &= -\mu(x, y)F(x, y) \end{aligned}$$

have the same trajectories if  $\mu(x, y) \neq 0$ . Use this for the prey-predator system

$$\begin{aligned} \dot{x} &= \alpha x - \beta xy \\ \dot{y} &= \gamma xy - \delta y \end{aligned}$$

to find a (nondegenerate) function  $H$  such that, when we restrict our interest to trajectories inside of the domain  $M = \{(x, y) : x, y > 0\}$ , all these trajectories lie in the level sets  $H(x, y) \equiv c$ . (5 points)

*Hint.* Use the Euler multiplier  $\mu(x, y) = 1/(xy)$ .