

Homework Assignments  
**Dynamical Systems II**  
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<http://dynamics.mi.fu-berlin.de/lectures/>  
**due date: Friday, December 21, 2018, 12:00**

**Problem 33:** [Grobman & Hartman]

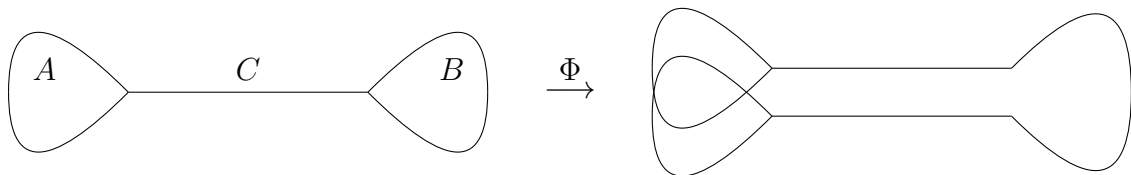
Consider the map  $\Phi(x) = Ax + f(x) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  with  $A$  a hyperbolic matrix. Show that there exists  $\varepsilon > 0$  such that for every function  $f \in B_\varepsilon(0)$

$$B_\varepsilon(0) := \left\{ g \in C^0(\mathbb{R}^2, \mathbb{R}^2) \mid g \text{ bounded and } \sup_{(x,y) \in \mathbb{R}^2} \frac{|g(x) - g(y)|}{|x - y|} < \varepsilon \right\}$$

there is a homeomorphism  $H$  of  $\mathbb{R}^2$  conjugating  $A$  to  $\Phi$ .

**Problem 34:** Try to realize the following graph by a continuous map  $\Phi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  (similar to the case of the Plykin attractor)

$$\begin{aligned} A &\rightarrow A \\ B &\rightarrow A \\ C &\rightarrow C + B - C \end{aligned}$$



- (i) Why does this construction not yield a hyperbolic attractor?
- (ii) Can  $\Phi$  contain a horseshoe?

**Problem 35:** Consider  $2 \times 2$  matrices  $A \in \text{SL}(2, \mathbb{Z})$  with integer coefficients and determinant 1. The linear map  $A$  on  $\mathbb{R}^2$  preserves orientation and area.

- (i) Prove that every  $A \in \text{SL}(2, \mathbb{Z})$  defines a diffeomorphism of the torus  $T^2 = \mathbb{R}^2 / \mathbb{Z}^2$ .
- (ii) Is  $A = \text{id} \in \text{SL}(2, \mathbb{Z})$  structurally stable?

*Extra credit:* Which  $A \in \text{SL}(2, \mathbb{Z})$  are structurally stable?

**Problem 36:** Consider the iteration on the 2-torus  $T = (\mathbb{R}/\mathbb{Z})^2$  defined by the matrix

$$B = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}.$$

Find a horseshoe for a suitable iterate  $B^k$ ,  $k > 0$ .

*Hint:* Identify the torus with the unit square  $[-1/2, 1/2)^2$  and investigate the images of a parallelogram parallel to the eigenvectors of  $B$ .